# HOMOGENEOUS DARBOUX POLYNOMIALS AND GENERALISING INTEGRABLE ODE SYSTEMS 

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#### Abstract

We show that any system of ODEs can be modified whilst preserving its homogeneous Darboux polynomials. We employ the result to generalise a hierarchy of integrable Lotka-Volterra systems.


1. Introduction. We are concerned with systems of Ordinary Differential Equations (ODEs),

$$
\begin{equation*}
\dot{\mathbf{x}}=\mathbf{f}(\mathbf{x}) \tag{1}
\end{equation*}
$$

where $\dot{\mathbf{x}}$ denotes the time derivative of a vector $\mathbf{x}$. A Darboux polynomial (or second integral) of (1) is a polynomial $P(\mathbf{x})$ such that $\dot{P}=C(\mathbf{x}) P$ for some function $C$ which is called the cofactor of $P[6]$. Darboux polynomials are important as the existence of sufficiently many Darboux polynomials implies the existence of a first integral, cf. Theorems 2.2 and 2.3 in [6]. Recently their use was extended to the discrete setting in [2].

In this paper, we propose the following generalisation of any ODE system of the form (1):

$$
\begin{equation*}
\dot{\mathbf{x}}=\mathbf{f}(\mathbf{x})+b(\mathbf{x}, t) \mathbf{x} \tag{2}
\end{equation*}
$$

where $b$ is a scalar function of $\mathbf{x}, t$. We will prove that if $P$ is a homogeneous Darboux polynomial for (1), then $P$ is also a Darboux polynomial for (2) with a modified cofactor.

We show that in several examples the above generalisation preserves the integrability of the ODE, e.g. this is the case for generalisations of: (i) the 2-dimensional system

$$
\begin{align*}
\dot{x} & =x^{2}+2 x y+3 y^{2}, \\
\dot{y} & =2 y(2 x+y), \tag{3}
\end{align*}
$$

found in [4, Appendix], (ii) the 4-dimensional Lotka-Volterra (LV) system

$$
\begin{align*}
\dot{x}_{1} & =x_{1}\left(+x_{2}+x_{3}+x_{4}\right) \\
\dot{x}_{2} & =x_{2}\left(-x_{1}+x_{3}+x_{4}\right) \\
\dot{x}_{3} & =x_{3}\left(-x_{1}-x_{2}+x_{4}\right)  \tag{4}\\
\dot{x}_{4} & =x_{4}\left(-x_{1}-x_{2}-x_{3}\right)
\end{align*}
$$

[^0]as well as (iii) higher dimensional LV systems found in [9]. For the LV systems we show that both Liouville integrability and superintegrability are preserved under certain generalisations given by (2).
2. Darboux polynomials and integrals/integrability. Note that if $P_{1}$ and $P_{2}$ are Darboux polynomials with cofactors $C_{1}$ and $C_{2}$ respectively, the product $P_{1}^{a} P_{2}^{b}$ is a Darboux polynomial with cofactor $a C_{1}+b C_{2}$. This implies that linear relations between cofactors give rise to integrals.

For the 2-dimensional system (3) three Darboux polynomials

$$
\begin{equation*}
P_{1}=x+y, \quad P_{2}=x-y, \quad P_{3}=y \tag{5}
\end{equation*}
$$

with cofactors given by

$$
\begin{equation*}
C_{1}=x+5 y, \quad C_{2}=x-y, \quad C_{3}=4 x+2 y \tag{6}
\end{equation*}
$$

respectively, were given in [6, Example 2.21]. As these cofactors satisfy the linear relation $C_{1}+3 C_{2}-C_{3}=0$, an integral is given by

$$
I=P_{1} P_{2}^{3} P_{3}^{-1}=\frac{(x+y)(x-y)^{3}}{y}
$$

The 4-dimensional LV system (4) admits linear Darboux polynomials of the form

$$
P_{i, j}=\sum_{k=i}^{j} x_{k}, \text { with } 1 \leq i \leq j \leq 4
$$

with corresponding cofactor

$$
C_{i, j}=-\sum_{k=1}^{i-1} x_{k}+\sum_{k=j+1}^{n} x_{k}
$$

Because

$$
C_{1,2}-C_{3,3}+C_{4,4}=\left(x_{3}+x_{4}\right)-\left(-x_{1}-x_{2}+x_{4}\right)+\left(-x_{1}-x_{2}-x_{3}\right)=0
$$

the rational function

$$
F=P_{1,2} P_{3,3}^{-1} P_{4,4}=\left(x_{1}+x_{2}\right) \frac{x_{4}}{x_{3}}
$$

is an integral. And similarly,

$$
C_{3,4}-C_{2,2}+C_{1,1}=\left(-x_{1}-x_{2}\right)-\left(-x_{1}+x_{3}+x_{4}\right)+\left(x_{2}+x_{3}+x_{4}\right)=0
$$

yields the rational integral

$$
G=P_{3,4} P_{2,2}^{-1} P_{1,1}=\left(x_{3}+x_{4}\right) \frac{x_{1}}{x_{2}}
$$

As $C_{1,4}=0$, the function

$$
H=P_{1,4}=x_{1}+x_{2}+x_{3}+x_{4}
$$

provides a third integral. The functions $F, G, H$ are functionally independent, as their gradients are linearly independent, and therefore the LV system (4) is superintegrable. The variables $u_{i}=P_{1, i}$ provide a separation of variables, i.e. each variable satisfies the same differential equation $\dot{u}_{i}=u_{i}\left(H-u_{i}\right)$ which can be explicitly integrated, cf. [1]

The system (4) is also a Hamiltonian system, with Hamiltonian $H$ and quadratic Poisson bracket, of rank 4,

$$
\begin{equation*}
\left\{x_{i}, x_{j}\right\}=x_{i} x_{j}, \quad i<j \tag{7}
\end{equation*}
$$

As both $F$ and $G$ Poisson commute with $H$, the systems $F, H$ and $G, H$, and hence the vector field (4), are Liouville integrable, cf. [9].
3. Generalising ODE systems. The following result is quite general, it generalises any ODE system (1) whilst preserving all homogeneous Darboux polynomials.

Theorem 3.1. Let $P(\mathbf{x})$ be a homogeneous Darboux polynomial of degree $d$ with cofactor $C(\mathbf{x})$ for the system of ODEs $\dot{\mathbf{x}}=f(\mathbf{x})$. Then $P$ is a Darboux polynomial for the system $\dot{\mathbf{x}}=\mathbf{f}(\mathbf{x})+b(\mathbf{x}, t) \mathbf{x}$, with cofactor $C+d b(\mathbf{x}, t)$, where $b$ is a scalar function of $\mathbf{x}, t$.

Proof. As $P$ is homogeneous of degree $d$, we have $\mathbf{x} \cdot \nabla P=d P$. As $P$ is a Darboux polynomial for $\dot{\mathbf{x}}=f(\mathbf{x})$, we have $\dot{P}=\nabla P \cdot \mathbf{f}=C P$. For the generalised system we then have

$$
\dot{P}=\nabla P \cdot(\mathbf{f}+b \mathbf{x})=C P+b d P=(C+d b) P
$$

We first apply Theorem 3.1 to the 2-dimensional system (3). With $b=a x+c y$ we obtain a generalisation of (3),

$$
\begin{align*}
& \dot{x}=x^{2}+2 x y+3 y^{2}+(a x+c y) x, \\
& \dot{y}=2 y(2 x+y)+(a x+c y) y . \tag{8}
\end{align*}
$$

Each $P_{i}, i=1,2,3$, given by (5), is a linear Darboux polynomial for the system (8) with modified cofactor $C_{i}^{\prime}=C_{i}+a x+c y$, where $C_{i}$ is given by (6). As

$$
(c-a-2) C_{1}^{\prime}-(a+c+6) C_{2}^{\prime}+2(a+1) C_{3}^{\prime}=0
$$

the function

$$
K=P_{1}^{c-a-2} P_{2}^{-(a+c+6)} P_{3}^{2(a+1)}=\frac{(x+y)^{c-a-2} y^{2(a+1)}}{(x-y)^{a+c+6}}
$$

is a first integral of (8).
Applying Theorem 3.1 to the 4-dimensional system (4), taking $b$ to be a constant, yields

$$
\begin{align*}
& \dot{x}_{1}=x_{1}\left(b+x_{2}+x_{3}+x_{4}\right) \\
& \dot{x}_{2}=x_{2}\left(b-x_{1}+x_{3}+x_{4}\right)  \tag{9}\\
& \dot{x}_{3}=x_{3}\left(b-x_{1}-x_{2}+x_{4}\right) \\
& \dot{x}_{4}=x_{4}\left(b-x_{1}-x_{2}-x_{3}\right)
\end{align*}
$$

whose Darboux polynomials $P_{i, j}$ now have cofactors $C_{i, j}^{\prime}=C_{i, j}+b$. In particular, $H=P_{1,4}$ is no longer an integral, and the linear combinations $C_{1,2}^{\prime}-C_{3,3}^{\prime}+C_{4,4}^{\prime}=$ $C_{3,4}^{\prime}-C_{2,2}^{\prime}+C_{1,1}^{\prime}=b$ do not vanish. We have to subtract the cofactor $C_{1,4}^{\prime}=b$, which corresponds to dividing by $H$. This yields two integrals

$$
F^{\prime}=\frac{\left(x_{1}+x_{2}\right) x_{4}}{\left(x_{1}+x_{2}+x_{3}+x_{4}\right) x_{3}}
$$

and

$$
G^{\prime}=\frac{\left(x_{3}+x_{4}\right) x_{2}}{\left(x_{1}+x_{2}+x_{3}+x_{4}\right) x_{1}} .
$$

The new system (9) is still Hamiltonian, with the same bracket (7). The new Hamiltonian

$$
H^{\prime}=H-b \ln \left(\frac{x_{1} x_{3}}{x_{2} x_{4}}\right)
$$

is no longer rational. The integrals $F^{\prime}, G^{\prime}, H^{\prime}$ are functionally independent, and so the system (9) is superintegrable. Moreover, the functions $F^{\prime}$ and $G^{\prime}$ Poisson commute with $H^{\prime}$, hence the systems $F^{\prime}, H^{\prime}$ and $G^{\prime}, H^{\prime}$ are Liouville integrable. In the next section we generalise this example to arbitrary even dimensions.
4. Integrability of a generalised $n$-dimensional LV system. In [9] the system of ODEs

$$
\begin{equation*}
\dot{x}_{i}=x_{i}\left(\sum_{j>i} x_{j}-\sum_{j<i} x_{j}\right), \quad i=1, \ldots, n \tag{10}
\end{equation*}
$$

arose as a subsystem of the quadratic vector fields associated with multi-sums of products, and it was shown to be superintegrable as well as Liouville integrable. Integrable generalisations of the system (10) have been obtained in $[3,5,7]$. The generalisation

$$
\begin{equation*}
\dot{x}_{i}=x_{i}\left(b+\sum_{j>i} x_{j}-\sum_{j<i} x_{j}\right), \quad i=1, \ldots, n \tag{11}
\end{equation*}
$$

of which (9) is a special case, seems to be new. In [9] the LV system of ODEs (10), with $n=2 r$ even, was shown to admit the integrals, for $k=1, \ldots, r$,

$$
\begin{align*}
F_{k} & =\left(x_{1}+x_{2}+\cdots+x_{2 k}\right) \frac{x_{2 k+2} x_{2 k+4} \cdots x_{n}}{x_{2 k+1} x_{2 k+3} \cdots x_{n-1}} \\
G_{k} & =\left(x_{n-2 k+1}+x_{n-2 k+2}+\cdots+x_{n}\right) \frac{x_{1} x_{3} \cdots x_{n-2 k-1}}{x_{2} x_{4} \cdots x_{n-2 k}} \tag{12}
\end{align*}
$$

The $n-1$ integrals $F_{1}, \ldots, F_{r-1}, G_{1}, \ldots, G_{r-1}, F_{r}=G_{r}=H=P_{1, n}$ were proven to be independent, and the sets $\left\{F_{1}, \ldots, F_{r-1}, H\right\},\left\{G_{1}, \ldots, G_{r-1}, H\right\}$ were proven to pairwise Poisson commute with respect to the bracket (7), which has rank $n$. Similar results were obtained for $n$ odd (here the rank of (7) is $n-1$ ), establishing the superintegrability as well as Liouville integrability of the $n$-dimensional LV system (10) for all $n$. We consider a generalisation of the even-dimensional system.

Theorem 4.1. The system

$$
\begin{equation*}
\dot{x}_{i}=x_{i}\left(b+\sum_{j>i} x_{j}-\sum_{j<i} x_{j}\right), \quad i=1, \ldots, n \tag{13}
\end{equation*}
$$

where $n=2 r$ is even, is both superintegrable and Liouville integrable.
Proof. The system is Hamiltonian with Hamiltonian

$$
H^{\prime}=H-b S, \text { with } S=\ln \left(\frac{x_{1} x_{3} \cdots x_{n-1}}{x_{2} x_{4} \cdots x_{n}}\right)
$$

According to Theorem 3.1 the functions (12) and $H$ are Darboux functions (functions $F$ such that $\dot{F}=C(\mathbf{x}) F$ for some $C$ ) with cofactor $b$. Therefore, $n-2$ integrals
are given by $F_{i}^{\prime}=F_{i} / H, G_{i}^{\prime}=G_{i} / H, i=1, \ldots, r-1$. Together with $H^{\prime}$ they form a set of $n-1$ integrals,

$$
\mathcal{S}=\left\{F_{1}^{\prime}, \ldots, F_{r-1}^{\prime}, G_{1}^{\prime}, \ldots, G_{r-1}^{\prime}, H^{\prime}\right\}
$$

for which we will prove functional independence, thereby showing the superintegrability of (13). The trick is to add a function, $H$, and show that the bigger set $\mathcal{S} \cup\{H\}$ is functionally independent, by showing the determinant of the Jacobian to be non-zero, which is done using LU-decomposition, cf. [8, Chapter 5]. We may perform row operations, which we do by taking linear combinations of the functions $H$ and $H^{\prime}$ and ordering the functions in a particular way:

$$
Z=\left(2\left(H-H^{\prime} / 2\right) / n^{2}, H / n^{2}, G_{n / 2-1}^{\prime}, F_{1}^{\prime}, G_{n / 2-2}^{\prime}, F_{2}^{\prime}, \ldots, G_{1}^{\prime}, F_{n / 2-1}^{\prime}\right)
$$

We then consider the scaled Jacobian $J=n^{2} \mathrm{Jac}(Z) / 2$ in the point $x_{1}=x_{2}=\cdots=$ $x_{n}=b=1$. The first two functions in $Z$ are chosen so the first two rows in $J$ are given by $J_{i, j}=i+j+1 \bmod 2(i=1,2)$.

We conveniently introduce two sets of elementary functions

$$
P_{i, j}=x_{i}+x_{i+1}+\cdots+x_{j}, \quad Q_{i, j}=x_{i}^{-1} x_{i+1} x_{i+2}^{-1} \cdots x_{j}^{(-1)^{j-i+1}}
$$

so that e.g. $F_{k}^{\prime}=\frac{P_{1,2 k} Q_{2 k+1, n}}{P_{1, n}}$. As

$$
\frac{\partial F_{k}^{\prime}}{\partial x_{i}}= \begin{cases}\frac{Q_{2 k+1, n}}{P_{1, n}}-\frac{P_{1,2 k} Q_{2 k+1, n}}{P_{1, n}^{2}} & i \leq 2 k \\ -(-1)^{i} \frac{P_{1,2 k} Q_{2 k+1, n}}{x_{i} P_{1, n}}-\frac{P_{1,2 k} Q_{2 k+1, n}}{P_{1, n}^{2}} & i>2 k\end{cases}
$$

we have

$$
\left.\frac{n^{2}}{2} \frac{\partial F_{k}^{\prime}}{\partial x_{i}}\right|_{\mathbf{x}=\mathbf{1}}= \begin{cases}\frac{n}{2}-k & i \leq 2 k \\ -(-1)^{i} k n-k & i>2 k\end{cases}
$$

In the point 1 the gradient of $G_{k}$ is the gradient of $F_{k}$ read from right to left. This yields, for $i>2$

$$
J_{i, j}= \begin{cases}-\left((-1)^{j} n+1\right)(n-i+1) / 2 & i \equiv 1, j<i \\ (i-1) / 2 & i \equiv 1, j \geq i \\ (n-i+2) / 2 & i \equiv 0, j<i-1 \\ \left((-1)^{j} n-1\right)(i-2) / 2 & i \equiv 0, j \geq i-1\end{cases}
$$

where (here and in the sequel) the equivalence is taken modulo 2. Explicitly, for $n=10$ we have

$$
J=\left(\begin{array}{cccccccccc}
1 & 0 & 1 & 0 & 1 & 0 & 1 & 0 & 1 & 0 \\
0 & 1 & 0 & 1 & 0 & 1 & 0 & 1 & 0 & 1 \\
36 & -44 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\
4 & 4 & -11 & 9 & -11 & 9 & -11 & 9 & -11 & 9 \\
27 & -33 & 27 & -33 & 2 & 2 & 2 & 2 & 2 & 2 \\
3 & 3 & 3 & 3 & -22 & 18 & -22 & 18 & -22 & 18 \\
18 & -22 & 18 & -22 & 18 & -22 & 3 & 3 & 3 & 3 \\
2 & 2 & 2 & 2 & 2 & 2 & -33 & 27 & -33 & 27 \\
9 & -11 & 9 & -11 & 9 & -11 & 9 & -11 & 4 & 4 \\
1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & -44 & 36
\end{array}\right) .
$$

We define lower and upper triangular matrices

$$
\begin{gathered}
L_{i, k}= \begin{cases}M_{i, k} & k=1,2 \\
1 & k=i \\
k /(n-k) & 1 \equiv i=k+1, k>2 \\
0 & \text { otherwise }\end{cases} \\
U_{k, j}= \begin{cases}M_{k, j} & k=1,2 \\
-n(n-k) / 2 & k \equiv 1, j \equiv 1, j \geq k \\
n(n-k+2) / 2 & k \equiv 1, j \equiv 0, j \geq k \\
-n^{2} /(n-k+1) & k \equiv 0, j \equiv 0, j \geq k \\
0 & k \equiv 0, j \equiv 0, j \geq k \text { or } k>j\end{cases}
\end{gathered}
$$

When $n=10$ we have

$$
\begin{aligned}
& L=\left(\begin{array}{cccccccccc}
1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
36 & -44 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
4 & 4 & \frac{3}{7} & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\
27 & -33 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\
3 & 3 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 \\
18 & -22 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\
2 & 2 & 0 & 0 & 0 & 0 & \frac{7}{3} & 1 & 0 & 0 \\
9 & -11 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\
1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 9 & 1
\end{array}\right), \\
& U=\left(\begin{array}{cccccccccc}
1 & 0 & 1 & 0 & 1 & 0 & 1 & 0 & 1 & 0 \\
0 & 1 & 0 & 1 & 0 & 1 & 0 & 1 & 0 & 1 \\
0 & 0 & -35 & 45 & -35 & 45 & -35 & 45 & -35 & 45 \\
0 & 0 & 0 & -\frac{100}{7} & 0 & -\frac{100}{7} & 0 & -\frac{100}{7} & 0 & -\frac{100}{7} \\
0 & 0 & 0 & 0 & -25 & 35 & -25 & 35 & -25 & 35 \\
0 & 0 & 0 & 0 & 0 & -20 & 0 & -20 & 0 & -20 \\
0 & 0 & 0 & 0 & 0 & 0 & -15 & 25 & -15 & 25 \\
0 & 0 & 0 & 0 & 0 & 0 & 0 & -\frac{100}{3} & 0 & -\frac{100}{3} \\
0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & -5 & 15 \\
0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & -100
\end{array}\right) .
\end{aligned}
$$

We now show that $J=L U$, making use of the Kronecker delta, $\delta_{i, k}=1$ if $i=k$ and 0 otherwise, and using summation over repeated indices. There are three cases:

- $i=1,2$. We have $L_{i, k}=\delta_{i, k}$, so $L_{i, k} U_{k, j}=U_{i, j}=M_{i, j}$.
- $1 \equiv i>2$. We have

$$
\begin{aligned}
L_{i, k} U_{k, j} & =(n-1)(n-i+1) U_{1, j} / 2-(n+1)(n-i+1) U_{2, j} / 2+U_{i, j} \\
& = \begin{cases}-\left((-1)^{j} n+1\right)(n-i+1) / 2 & i>j \\
(n-1)(n-i+1) / 2-n(n-i) / 2=(i-1) / 2 & 1 \equiv j \geq i \\
-(n+1)(n-i+1) / 2+n(n-i+2) / 2=(i-1) / 2 & 0 \equiv j \geq i\end{cases}
\end{aligned}
$$

- $0 \equiv i>2$. We have

$$
\begin{aligned}
L_{i, k} U_{k, j} & =(n-i+2)\left(U_{1, j}+U_{2, j}\right) / 2+(i-1) U_{i-1, j} /(n-i+1)+U_{i, j} \\
& = \begin{cases}\frac{n-i+2}{2} & j<i-1 \\
\frac{n-i+2}{2}-\frac{(i-1) n(n-i+1)}{2(n-i+1)}=-\frac{(i-2)(n+1)}{2} & 1 \equiv j \geq i \\
\frac{n-i+2}{2}+\frac{(i-1) n(n-i+3)}{2(n-i+1)}-\frac{n^{2}}{n-i+1}=\frac{(i-2)(n-1)}{2} & 0 \equiv j \geq i\end{cases}
\end{aligned}
$$

As both $L$ and $U$ have non-zero diagonal elements, the determinant of $J$ is non-zero. Hence the set $S$ is functionally independent. This shows that (13) is superintegrable.

Next we prove that each pair of functions in the set $\left\{F_{1}^{\prime}, \ldots, F_{r-1}^{\prime}, H^{\prime}\right\}$ Poisson commutes with respect to the bracket (7). Due to the Leibniz rule, the brackets $\left\{F_{i}^{\prime}, F_{j}^{\prime}\right\}=\left\{F_{i} / H, F_{j} / H\right\}$, with $1 \leq i, j<r$, can be expressed in terms of $\left\{F_{i}, F_{j}\right\}$, $\left\{F_{i}, H\right\},\left\{H, F_{j}\right\}$, which all vanish. We also have $\left\{F_{i}^{\prime}, H^{\prime}\right\}=0$ as the $F_{i}^{\prime}$ are integrals and $H^{\prime}$ is the Hamiltonian function of the system. Similarly, it follows that the functions in $\left\{G_{1}^{\prime}, \ldots, G_{r-1}^{\prime}, H^{\prime}\right\}$ Poisson commute. This shows that (13) is Liouville integrable.

Remark 1. Similar to the above, one can also show that the system

$$
\begin{equation*}
\dot{x}_{i}=x_{i}\left(b(S)+\sum_{j>i} x_{j}-\sum_{j<i} x_{j}\right), \quad i=1, \ldots, n=2 r \tag{14}
\end{equation*}
$$

where $b$ is an arbitrary integrable function, is both superintegrable and Liouville integrable. The system (14) is a Hamiltonian system with Hamiltonian $H^{*}=$ $H-B(S)$, where $B$ is the anti-derivative of $b$.

Remark 2. In general, the b-generalisation (2) of a Hamiltonian system (1) will not be Hamiltonian. We hope to discuss some other cases in which the generalisation is Hamiltonian in a future publication. The reason that we have restricted the dimension of the Lotka-Volterra systems (13) to be even is that it seems unclear whether a Hamiltonian exists in the general odd-dimensional case.

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